

# CONTENTS

<b>Preface</b>	<b>ix</b>
<b>Acknowledgments</b>	<b>xv</b>
<b>List of Symbols</b>	<b>xvii</b>
<b>1. Convex sets</b>	<b>1</b>
1. Introduction, 1	
2. Convex sets and cones, 1	
3. Functions valued in a convex set, 6	
4. Notes, 7	
<b>2. Matrix theory background</b>	<b>9</b>
1. Introduction, 9	
2. The Jordan and real canonical forms, 9	
3. Nonnegative matrices, 15	
4. $M$ -matrices, 19	
5. The Frobenius normal form, 24	
6. Notes, 29	
<b>3. Differential and control system preliminaries</b>	<b>31</b>
1. Introduction, 31	
2. Linear differential systems, 31	
3. Linear control systems: controllability, observability, and realizability, 35	
4. Glossary of models, 54	
5. Notes, 58	
<b>4. Exponentially nonnegative matrices</b>	<b>61</b>
1. Introduction, 61	
2. Holdable closed convex sets: geometric considerations, 65	

3. Exponentially nonnegative matrices, 70	
4. Notes, 83	
<b>5. Extended <math>M</math>-matrices</b>	<b>85</b>
1. Introduction, 85	
2. Extended $M$ -matrices, 86	
3. Further results, 88	
4. Notes, 91	
<b>6. Cone reachability</b>	<b>93</b>
1. Introduction, 93	
2. Basic properties of reachability cones, 94	
3. Cone reachability: simple cases, 98	
4. Cone reachability: the case of a real spectrum, 102	
5. The boundary of the reachability cone, 110	
6. Cone reachability for discrete approximations to the differential equation, 115	
7. Notes, 124	
<b>7. Applications to feedback control</b>	<b>125</b>
1. Introduction, 125	
2. Feedback holdability of $R_+^n$ , 126	
3. Controllability to $R_+^n$ , 129	
4. A stabilizability-holdability problem, 132	
5. Notes, 134	
<b>8. Controllability, observability, and realizability of positive control systems</b>	<b>137</b>
1. Introduction, 137	
2. Controllability with nonnegative controls, 137	
3. Observability with conical observation set, 146	
4. Positive realization, 155	
5. Notes, 159	
<b>References</b>	<b>161</b>
<b>Index</b>	<b>165</b>