PART B

NOVEL MECHANISMS, ROBOTS, AND THEIR APPLICATIONS

DETC2009-86074 ........................................................................................................ 627
The Establishment of Novel Structure Representation Models for Several Kinds of
Mechanisms
Huafeng Ding, Jing Zhao, and Zhen Huang

DETC2009-86213 ........................................................................................................ 633
Self Motions of the Pantopteron
Sébastien Briot and Ilian A. Bonev

DETC2009-86281 ........................................................................................................ 639
Workspace Investigation of a Novel Parallel Manipulator
Yanwen Li, Fengfeng Xi, Lumin Wang, Yueyue Zhang, and Huang Zhen
DETC2009-86247
An Inertially-Actuated Passive Dynamic Step Climbing Wheeled Robot
  John Humphreys and Dennis Hong

DETC2009-86529
Impedance Control of Manipulators With Heavy Payload for Spacecraft Rendezvous and Docking Simulators
  Farhad Aghili

DETC2009-86541
On the Effect of Contact Friction and Contact Compliance on the Grasp Performance of Underactuated Hands
  Gert A. Kragten, H. Allert Bosch, Teunis van Dam, Johan A. Slobbe, and Just L. Herder

DETC2009-86677
Observer Design to Estimate Shank Angle for Motion Control of an Underactuation Biped Robot
  Reza Dehghani and Abbas Fattah

DETC2009-86700
Reactionless Two-Degree-Of-Freedom Planar Parallel Mechanism With Variable Payload
  Alexandre Lecours and Clément Gosselin

DETC2009-86789
Dynamic Analysis of a Specific 2PRR Robotic Manipulator
  Philip A. Voglewede and Robert Copsey

DETC2009-87069
Bipedal Robot Walking Cycle Forces and Torques Prediction and an Inverse System and Gain Scheduling Based Control
  Elvedin Kljuno and Robert L. Williams II

DETC2009-87132
Maximum Virtual Stiffness Distribution Analysis and Measurement for Haptic Device
  Xiaowei Dai, Yuru Zhang, and Dangxiao Wang

DETC2009-87303
Robust Variable Structure Control for Free-Floating Space Robot System With Dual-Arms in Joints Space
  Xiaoteng Tang and Chen Li

DETC2009-87513
Optimal Throwing Motion Planning for a Biped Human Mechanism
  Joo H. Kim, Yujiang Xiang, Jingzhou (James) Yang, Karim Abdei-Malek, and Jasbir S. Arora

DETC2009-87639
An Human-Robot Interaction Control Architecture for an Intelligent Assistive Robot
  Maurizio Ficocelli, Goldie Nejat, and Greg Minseok Jhin
ROBOT KINEMATICS AND MOTION PLANNING

DETC2009-86162
Solving the Kinematics of a Parallel Robot Based on CAD Variation Geometry
   Jiayin Xu, Yi Lu, and Jingjing Yu .......................... 947

DETC2009-86175
Solving Inverse Kinematics and Driving Forces of a Novel 3RPS-3SPR Serial-Parallel
   Manipulator
   Bo Hu, Yi Lu, Jia Yin Xu, and Jing Jing Yu .......................... 955

DETC2009-86227
Estimation of the Center of Mass Using Statically Equivalent Serial Chain Modeling
   Sebastien Cotton, Andrew Murray, and Philippe Fraisse .......................... 961

DETC2009-86261
Singularity Analysis of 5-RPRRR Parallel Mechanisms via Grassmann Line Geometry
   Mehdi Tale Masouleh and Clément Gosselin .......................... 969

DETC2009-86408
Generation of Under-Actuated Parallel Robots With Non-Holonomic Joints and Kinetostatic
   Analysis of a Case Study
   Patrick Grosch, Raffaele Di Gregorio, and Federico Thomas .......................... 979

DETC2009-86595
Design of a Biped Robot With Torsion Springs at the Joints for Reduced Energy
   Consumption During Walk
   Santosh Pratap Singh, Ashish Dutta, and Anupam Saxena .......................... 987

DETC2009-86714
Kinematics of a Prism-Type Translational Robot
   Chung-Ching Lee and Po-Chih Lee .......................... 993

DETC2009-86912
Analysis, Synthesis, and Experiments of Standing Up Methods for a Tripedal Robot
   Ivette M. Morazzani and Dennis W. Hong .......................... 1003

DETC2009-86923
Gait and Gait Transition for a Robot With Two Actuated Spoke Wheels
   Ya Wang, Ping Ren, and Dennis Hong .......................... 1017

DETC2009-86925
Considerations for Motion Planning of a Robot With Two Actuated Spoke Wheels in the
   Two-Dimensional Sagittal Plane: Gaits and Transitions
   Shawn C. Kimmel and Dennis W. Hong .......................... 1027

DETC2009-86934
Redundancy Resolution Using Tractrix: Simulations and Experiments
   V. C. Ravi, Subrata Rakshit, and Ashitava Ghosal .......................... 1037
Optimal Motion Planning of Manipulators With Elastic Links and Joints in Generalized Point-To-Point Task
H. N. Rahimi, M. H. Korayem, and A. Nikoobin

Branch Identification of Planar Two-DOF Seven-Bar Linkages
Jun Wang, Kwun-Lon Ting, and Changyu Xue

THEORETICAL AND COMPUTATIONAL KINEMATICS

A Systematical Approach for Structure Synthesis of Parallel Mechanisms Based on Single-Open-Chain Modules and Its Application
Ting-Li Yang, An-Xin Liu, Qiong Jin, Yu-Feng Luo, Lu-Bin Hang, and Hui-Ping Shen

Infinitesimal Kinematics Methods in the Mobility Determination of Kinematic Chains

Slider Cranks as Compatibility Linkages for Parameterizing Center Point Curves
David H. Myszka and Andrew P. Murray

Improving the Efficiency of Protein Conformation Prediction With Energy Landscape Modification
Temsiri Sapsaman and Harvey Lipkin

On the Topological Representation and Compatibility of Variable Topology Mechanisms
Win-Bin Shieh, Frederick Sun, and Dar-Zen Chen

Position Analysis of a Bennett-Based Multiple-Mode 7R Linkage
Chintien Huang, Xianwen Kong, and Tzuhsiu Ou

Singularity-Free Taskspace Optimization of 6-RSS Mechanisms
Hao Li, Yuru Zhang, and Yi Yang

Geometric and Kinematic Analysis of the Hoberman Switch-Pitch Ball and Its Variant
Guowu Wei, Xilun Ding, and Jian S. Dai

On the Mobility of Spatial Group 2 Mechanisms
Kwun-Lon Ting, Changyu Xue, Jun Wang, and Kenneth R. Currie