# TABLE OF CONTENTS

## PLENARY SESSION: NAVIGATING THE EARTH AND BEYOND
**General Chair:** Dr. M. Elizabeth Cannon, The University of Calgary, Department of Geomatics Engineering  
**Technical Program Chair:** Dr. Penina Axelrad, University of Colorado

GPS Land Vehicle Applications,  
R. Denaro, Motorola Position and Navigation Systems Business .......................................................... 3-4

Marine Navigation and Surveying Developments,  
G. Lachapelle, The University of Calgary ........................................................................................................ 5-11

Airborne Applications,  
M. Kayton, Kayton Engineering Company ..................................................................................................... 13

Space Applications,  
W. Melbourne, Jet Propulsion Laboratory ...................................................................................................... 15

## SESSION 1A: NAVIGATION INTEGRITY - RAIM ALGORITHMS AND REQUIREMENTS
**Chair:** Ms. Marie Lage, Stanford Telecommunications, Inc.

Assessment and Refinements of RAIM Certification Procedures for FAA/DoD Receivers,  
P. Munjal and S. Sedlacek, The Aerospace Corporation .............................................................................. 19-29

Extending the Generality and Robustness of RAIM Algorithms,  
E. Copps and L. Lupash, Intermetrics, Inc. .................................................................................................. 31-39

Integrity Testing for GNSS Sole Means,  
J. Farrell, Navigil; F. van Grass, Ohio University ....................................................................................... 41-50

Comparison of FDE and FDI RAIM Algorithms for GPS,  
R. G. Brown, Iowa State University; J. Kraemer and G. Nim, Volpe National Transportation Systems Center .... 51-60

## SESSION 1B: GPS TECHNOLOGY
**Chair:** Ms. Debra Diefes, Adroit Systems, Inc.

The All-Purpose D/GPS Signal Model,  
M. Braasch, Avionics Engineering Center, Ohio University ........................................................................... 63-67

Theory and Design of Pseudolites,  
H. S. Cobb, C. Cohen and B. Parkinson, Department of Aeronautics & Astronautics, Stanford University .......... 69-75

Testing and Analysis of Baseline Length as a Performance Factor in GPS Attitude Determining Systems (ADS),  
C. Rodgers, A. Gardner, and D. Stroup, Adroit Systems, Inc. ........................................................................ 77-83

Position Measurements Near a Power Transmission Line,  
K. Fitzgibbon, F. Walter, A. Lacava, and L. Cividanes, Instituto Tecnologico de Aeronautica ......................... 85-88

## SESSION 1C: TIME TRANSFER
**Chair:** Dr. Quyen D. Hua, Stellar GPS Corporation  
**Co-Chair:** Dr. Edward Powers, Naval Research Laboratory

TOE Control for Northwest European Loran System (NELS),  
E. Bailey, Megapulse, Inc.; D. Sennedot, DCN Brest (DGA); F. Hubert, Cap Gemini Sogeti .......................... 91-98

Test Results and Analysis of a Low Cost Core GPS Receiver for Time Transfer Application,  
M. King and D. Busch, Motorola Inc. (PNSB); M. Miranian, U.S. Naval Observatory ..................................... 99-109

Development of an Accurate Transmission Line Fault Locator Using the Global Positioning System,  
H. Lee, B.C. Hydro and Power Authority ..................................................................................................... 111-116

Time Transfer Test Results Using the INMARSAT Geostationary Overlay,  
A. Brown and T. Kelecy; NAVSYS; D. Davis, NIST; R. Walton, COMSAT ..................................................... 117-123
SESSION 2A: NAVIGATION INTEGRITY - WIDE AREA AND LOCAL DGPS MONITORING
Chair: Mr. George Kinal, Inmarsat

Integrity Concepts for a GPS Wide-Area Augmentation System (WAAS),
R. Loh and J. Fernow, Center for Advanced Aviation System Development, The MITRE Corporation .......................... 127-135

Integrity of GNSS for Civil Air Navigation in Japan,
K. Hoshinoo, Electronic Navigation Research Institute, Ministry of Transport of Japan .................................................. 137-143

Integrity Monitoring Strategies for GNSS Applications,
S. Vieweg, Inst. of Flight Guidance & Control, TU Braunschweig; W. Lechner, Avionics Center Braunschweig ......................... 145-153

Autonomous Integrity Monitoring and Wide Area DGPS,
T. Walter, B. Pervan and P. Enge, Stanford University; J. Herendeen and P. Levin, WPI ......................................................... 155-163

Analysis of Use of Receiver Autonomous Integrity Monitoring (RAIM) in a GPS Wide-Area Augmentation System (WAAS),
Y. Lee, The MITRE Corporation .......................................................... 165-174

DGPS Ground Station Integrity Monitoring,
T. Skidmore and F. van Graas, Ohio University ........................................ 175-183

Availability Assessment of Alternative Precision Approach and Landing System Architectures,
K. Markin, P. Wroblewski, T. Hsiao and W. Poor, The MITRE Corporation ................................................................. 185-192

SESSION 2B: RADIONAVIGATION TECHNOLOGY
Chair: Mr. John Beukers, Beukers Technology

GLONASS P-Code Data Message,
P. Daly and S. Riley, Department of Electronic and Electrical Engineering, The University of Leeds ......................... 195-202

Integrated GPS/Loran-C Receivers: A Perspective on User Acceptance, Integration Schemes, and Certification Status,
R. Anoll, Systems Control Technology, Inc ........................................ 203-207

Satellite and Terrestrial Radionavigation - A Partnership,
A. Stratton, Navigation Consultant ...................................................... 209-218

Selection of a Localizer Array for Use When Large Buildings are Present,
R. McFarland and D. Quinet, Avionics Engineering Center, Ohio University ......................................................... 219-229

Studies and Performance of a New Technique for Mitigation of Pseudorange Multipath Effects in GPS Ground Stations,
G. Bishop, Phillips Lab.; D. Coco and P. Kappler, Applied Research Labs; E. Holland, Northwest Research ...................... 231-242

SESSION 2C: NAVIGATION AND COMMUNICATION SYSTEMS INTEGRATION
Chair: Mr. George Zachmann, Comsat Mobile Communications
Co-Chair: Mr. Michael King, Motorola Position and Navigation Business

Navigation and Communications Systems Integration,
R.W. Kelly, Orbital Communications Corporation ........................................ 245-250

Combined Transmission of DOD-FAA Signal Structures from CAG,
M. Ananda, P. Munjal, R. Sung and K. Woo, The Aerospace Corporation .................. 251-260

Vehicle GPS Positioning Over Cellular Networks,
M. Sushko, Kensington & Icknield, Ltd ................................................ 261-275

The Equivalence of TOA and TDOA RF Transmitter Location,
P. Rusu, Applied Research Laboratories, The University of Texas at Austin .................. 277-286

Integration of Vehicular Navigation and MOBITEX Wireless Packet Data Network,
T. Yang, RAM Mobile Data, USA Limited Partnership; K. Yip, RAM/BSE Systems Development, Inc .......................... 287-293

Combat Survivor Evader Locator (CSEL), A New Method for Locating Survivors,
D. Pinkard, Space and Naval Warfare Systems Command ......................... 295-300
SESSION 3A: CIVIL AND MILITARY AIRBORNE APPLICATIONS
Chair: Ms. Karen Van Dyke, DOT/Volpe Center

An Adaptation of Global Positioning System (GPS) Technology to Air Traffic Control (ATC),
H. Hodges, Crown Communications, Inc ................................................................. 303-313

GPS Application to General Aviation Collision Avoidance,
J. Baldwin and A. Smith, Rannoch Corporation ......................................................... 315-321

GPS NOTAM Procedures,

Civil Satellite Augmentation of GPS,

Differential Inertial Filter for Dynamic Sensor Alignment,
N. Carlson, Integrity Systems; R. Kelley, McDonnell Douglas Aerospace; S. Berning, USAF Wright Laboratory 341-351

Weapon System Performance Analysis for an I^2R Seeker Integrated with INS/GPS,
D. Kelly and M. Heiman, Sverdrup Technology, Inc .................................................... 353-362

Issues for Robust Implementation of Relative GPS Guidance for Precision Weapon Delivery,
M. Youhanaie and F. Ziolkowski, Hughes Aircraft Co.; N. Pujara, USAF Wright Laboratory 363-368

SESSION 3B: SPACE APPLICATIONS - ORBIT AND ATTITUDE DETERMINATION METHODOLOGY
Chair: Dr. Willy Bertiger, Jet Propulsion Laboratory

New Ground and Space-Based GPS Tracking Techniques for High-Earth and Deep Space Orbit Determination Applications,
S. Lichten, D. Sweeney, B. Haines, L. Young, C. Dunn, S. Nandi, F. Srinivasan, & D. Spitzmesser, Jet Propulsion Lab 371-380

Autonomous Integrated GPS/CES/SS Navigation for High-Altitude Orbits,
J. Galdos, T. Upadhyay, A. Kumar, and B. Wu, Mayflower Communications Company, Inc.;
J. Lomas and R. French, NASA Marshall Space Flight Center .................................... 381-392

Ranging Signal Control and Ephemeris/Time Determination for Geostationary Satellite Navigation Payloads,
A.J. Van Dierendonck, Inmarsat; B. Elrod, Stanford Telecommunications 393-402

On the Use of the Global Positioning System for Orbit Determination of Low Flying Satellites,
I. Osorio, Observatorio Astronomico .............................................................................. 403-412

First Results from PoSAT-1 GPS Experiment,
M. Unwin and M. Sweeting, CSER, University of Surrey 413-420

RADCAL: Precision Orbit Determination with a Commercial Grade GPS Receiver,
J. Langer, W. Feess, K. Harrington, and M. Bacigalupi, The Aerospace Corporation;
M. Cardoza, R. Mach and P. Abusali, Applied Research Laboratories, The University of Texas at Austin 421-431

Optimal GPS Attitude Determination without Ambiguity Resolution,
L. Weill, Magellan Systems Corporation & California State University, Fullerton 433-439

On-Orbit GPS Based Attitude and Antenna Baseline Estimation,
P. Axelrad and L. Ward, University of Colorado ............................................................. 441-450

SESSION 3C: NAVIGATION AND POSITIONING EXPERIENCES
Chair: Col. Zdzislaw (Stan) Lewantowicz, USAF-Wright Patterson
Co-Chair: Mr. Samuel G. Shaw, California Maritime Academy

Dynamic GPS Positioning on the Bayou,

Training Experiences with GPS in the Merchant Marine,
S. Shaw and J. Keever, California Maritime Academy .................................................. 457-464

GPS Field Testing - The Untold Stories,
D. Abby, Intermetrics, Inc ............................................................................................... 465-494

Brazilian ADS and DGPS Trials,
K. Fitzgibbon and F. Walter, Instituto Tecnologico de Aeronautica ................................ 495-501

NAVSTAR GPS and GLONASS - Competitors or Initial Elements of a Future Civil GNSS,
S. Vieweg, Institute of Flight Guidance & Control, TU; W. Lechner, Avionics Center Braunschweig 503-509
Isolation of GPS Multipath and Receiver Tracking Errors,  
M. Braasch, Avionics Engineering Center, Ohio University

Field Results from a Realtime Precise Positioning System,  
M. Cardoza, M. Leach, and A. Tucker, Applied Research Laboratories,  
University of Texas at Austin

An Application of Relative GPS,  
N. Weinman, J. Campanile, NCCOSC RDT&E Division Warminster Detachment;  
P. Howe, Wright Patterson AFB; C. Sives, N. Acharya and M. Park, Galaxy Scientific Corporation

SESSION 4A: LAND VEHICLE APPLICATIONS  
Chair: Mr. James Chadwick, The MITRE Corporation  
Co-Chair: Mr. Jonathan Ladd, Ashtech Inc.

Mobile Data Communication in Land-Based Positioning,  
Navigation and Surveying Applications,  
T. Yang, RAM Mobile Data USA Limited Partnership;  
K. Yip, RAM/BSE Systems Development, Inc.

GPS System Integration and Field Approaches in Precision Farming,  
H. Gehue, G. Lachapelle and M. E. Cannon, Department of Geomatics Engineering, The University of Calgary;  
T. W. Goddard and D. C. Penney, Conservation and Development Alberta Agriculture

OEM GPS Sensor Board Testing for Land and Marine Applications,  

An Augmented Inertial Navigation System for Autonomously Guided Vehicles,  
W. Ebert, T. Krieg, and J. Schnell, LITEF GmbH

GPS Aided Dead Reckoning Navigation,  
R. Zickel and N. Nehemia, RAFAEL

Real-Time cm-level GPS Positioning of Cutting Blade and Earth Moving Equipment,  
G. Dedes and C. Goad, Center for Mapping Department of Geodetic Science, The Ohio State University

GPS Surveying in an Urban Environment Under AS,  
I. Webster, J. Nolan, S. Gourevitch, and X. Qin, Ashtech, Inc.

SESSION 4B: SPACE APPLICATIONS - ORBIT DETERMINATION PERFORMANCE  
Chair: Dr. Jorge Galdos, Mayflower Communications Company, Inc.

Accuracy of GPS Determined TOPEX/Poseidon Orbits During Anti-Spoof Periods,  
R. Muellerschoen, W. Bertiger, S. Wu, T. Munson,  
J. Zumberge and B. Haines, Jet Propulsion Laboratory

Processing DORIS Data with the GIPSY/OASIS II Software: Recent Results for Point Positioning and Orbit Determination,  
P. Willis, Institut Geographique National; W. Bertiger, Jet Propulsion Laboratory

A Study of Real Time Orbit Determination for the Extreme Ultraviolet Explorer,  
K. Gold, W. Bertiger, T. Yunck, S. Wu and R. Muellerschoen, Jet Propulsion Laboratory;  
G. Born and K. Larson, University of Colorado

Direct Satellite Tracking Using GPS,  

Orbital Navigation with a GPS Receiver on the H.E.T.E Spacecraft,  
J. L. Issler, R. Mesnard, M. Tello and E. Péragin, C.N.E.S; F. Martel, AeroAstro Inc;  
G. Ricker, MIT; G. Cailliet, C. Mehlern, and C. Valpard, SEXTANT Avionique

The First Flight Tests of GPS on the Space Shuttle,  
P. Saunders, NASA Johnson Space Center; M. Robel, M. Aerni,  
D. Feuerstein and S. Lowery, Lockheed Engineering Sciences Co.; C. Cohen, Stanford University

GPS/IMU/Laser Space Mission for Global Change Sensing & 21st Century Satellite Control,  
D. Gleason, U.S. Air Force Phillips Laboratory
SESSION 4C: INERTIAL INSTRUMENTS AND SENSOR TECHNOLOGY
Chair: Mr. John Anselmo, Hughes Aircraft Co.
Co-Chair: Mr. Douglas MacGugan, Sundstrand Data Control

FOG Based Inertial Strapdown System for Online Borehole Measurement,
G. Mutter, H. Malthan, M. Hafen, and C. Noxon, LITEF GmbH ................................. 681-694
"SMART" Gyro Miniature Gyro Electronics,
H. Hog and W. Fuchs, LITEF GmbH ................................................................. 695-704
Design of Experiments for QUBIK Inertial Measurement Unit,
M. Morrison, Loral Consultant, Loral Control Systems ........................................... 705-715

SESSION 4D: ELECTRONIC CHARTING
Chair: Mr. Peter Kielland, Canadian Hydrographic Service

ECDIS: Revolutionary or Evolutionary?,
S. Ford, Texas A&M University at Galveston ...................................................... 719-728
1993 At Sea Evaluation of ECDIS,
I. Gonin and M. Dowd, U.S. Coast Guard, Research & Development Center ........ 729-738
Field Trials of "HANS" in the Houston Ship Channel,
C. Weeks, Hydrographic Associates, Inc. ......................................................... 739-746
Dead Reckoning/Target Tracking in an ECDIS Environment,
E. Baziw, Offshore Systems, Ltd. ................................................................. 747-756

SESSION 5A: PRECISION AIRCRAFT POSITIONING AND LANDING APPLICATIONS
Chair: Dr. Michael Braasch, Ohio University

Performance of Category IIIB Automatic Landings Using C/A Code Tracking Differential GPS,
S. Rowson and G. Courtney, Wilcox Electric; R. Hueschen, NASA Langley Research Center ................................................. 759-767
Flying the Tunnel -- System Engineering Tradeoffs Among Accuracy, Availability, Continuity,
and Integrity for Category-1 Precision Approach,
B. DeCleene, Advanced Management Technology, Inc.; S. Heppe, Stanford Telecommunications, Inc. .................. 769-778
Ambiguity Resolution of GPS L1 Carrier-Wave Measurements for High Precision Aircraft Navigation,
B. Tiemeyer and G. Schanzer, Institute of Flight Guidance & Control, TU Braunschweig;
M. E. Cannon and G. Lu, Department of Geomatics Engineering, The University of Calgary; ...................... 779-792
Precise Aircraft-to-Aircraft Positioning Using a Multiple Receiver Configuration,
An Investigation of Airborne GPS/INS for High Accuracy Position and Velocity Determination,
H. Sun, M. Cannon, Department of Geomatic Engineering, The University of Calgary;
T. Owen and M. Meindl, Sandia National Laboratories ........................................ 801-809
Error Sources in GPS-Determined Acceleration for Airborne Gravimetry,
Synergistic Effects of Doppler Radar/GPS Navigation Integration and the
Development of an Advanced Navigation System for Helicopter Applications,
H. Buell and A. Hunton, GEC Marconi Electronic Systems Corporation .................. 821-830

SESSION 5B: MARINE NAVIGATION AND SURVEYING
Chair: Capt. Benjamin Peterson, U.S. Coast Guard Academy

Performance Comparison of Candidate U.S. Coast Guard WADGPS Network Architectures,
K. T. Mueller and M. Biester, TAU Corporation; P. Loomis, Trimble Navigation, Ltd. ......................... 833-841
Coverage Prediction of DGPS Radio-Beacon System,
D. Poppe, D. Last and M. Searle, University of Wales ....................................... 843-850
Joint Federal Efforts in Establishing a Differential GPS System for Navigable Rivers,
S. Frodge and J. Garster, U.S. Army Corps of Engineers; J. Radice, U.S. Coast Guard ........................................... 851-858

High Accuracy Underwater Surveying in Support of the US Navy’s
Intermediate Scale Measurement System,
S. Cannon, Pelagos Corporation; J. Miller, Naval Facilities Engineering Service Center, Port-Hueneme ...................... 859-868

On Estimating Map Model Errors and GPS Position Errors
(Applying More Science to the Art of Navigation),
P. Kielland, Canadian Hydrographic Service; T. Tubman, Nortech Surveys Canada .......................................................... 869-881

Results of Real-Time Testing & Demonstration of the U.S. Army Corps of Engineers
Real-Time On-The-Fly Positioning System,
S. Frodge, U.S. Army Corps of Engineers; B. Remondi, National Geodetic Survey;
D. Lapucha, John E. Chance Associates, Inc. ................................................................. 883-892

Test Results of GPS Based Attitude Determining System for Marine Navigation,
D. Diefes, G. Hazel, and D. Greenlee, Adroit Systems, Inc ........................................... 893-899

Kalman Filtering and Optimal Control Strategies for Dynamic-Positioning Systems,
Y. Feng and K. Kubik, Space Center for Satellite Navigation, Queensland University of Technology ........................ 901-907

SESSION 5C: ATMOSPHERIC STUDIES
Chair: Mr. John A. Klobuchar, U.S. Air Force Phillips Laboratory

Ionospheric Effect Modelling for Single Frequency GPS Users,
W. Qiu, G. Lachapelle, and M. E. Cannon, Department of Geomatics Engineering, The University of Calgary .......................... 911-919

A Real Time Ionospheric Model for Use in a WADGPS System,
O. Håkegård, The Norwegian Institute of Technology .......................................................... 921-926

Development of an Error Budget for a GPS Wide-Area Augmentation System (WAAS),
M. B. El-Arini, C. Hegarty and J. Fernow, The MITRE Corporation;
J. Klobuchar, U.S. Air Force Phillips Laboratory ............................................. 927-936

Modeling of GPS L1L2 Signal Propagation through the Ionosphere,
J. Anselmo, Hughes Aircraft Company .................................................. 937-942

Small Scale Anomalies in Omega Position Data Revealed with GPS,
R. Barr, National Institute of Water & Atmospheric Research; T.R. Armstrong, Industrial Research, Ltd.;
S. Arrell, 40 Squadron, Royal New Zealand Air Force .................................................. 943-951

First Experiences with the DGPS Reference Station DIRES,
E. Engler, A. Jungstand, and D. Klaehn, German Aerospace Research Establishment (DLR) ......................... 953-960

Evaluation of the GPS Wide-Area Augmentation System (WAAS) Ionospheric Grid Algorithm
During the Peak of the Current Solar Cycle,
and P. Doherty, Boston College .......................................................... 961-968

AUTHORS INDEX .......................................................................................................................... 969-971

CONFERENCE REGISTRANTS .................................................................................................. 973-980