# TABLE OF CONTENTS

**Plenary Session: GPS GOES OPERATIONAL: APPLICATIONS AND TECHNOLOGY**

**Way Points for Radio Navigation in the 21st Century**  
Olaf Lundberg, INMARSAT .......................................................... 3-15

**Maintenance and Enhancement of the World Geodetic System 1984**  
Stephen Malys and James Slater, Defense Mapping Agency .................. 17-24

**Civil GPS Timing Applications**  
David Allan, Allan’s TIME, Inc.; Jack Kusters and Robin Giffard, Hewlett Packard Company .................. 25-32

**GPS Dual Use Opportunities**  
Col. Michael Wiedemer, U.S. Air Force ........................................ 33-47

**Session A1: GPS/GIS INTEGRATION**

**Comparison of Methods for Obtaining Absolute WGS 84 Position in Remote Locations**  
John Brown, Dr. M. Elizabeth Cannon, and Douglas Roberts, The University of Calgary;  
James G. Morgan, Chevron Petroleum Technology Company, Inc. .................. 51-60

**GPS/GIS and Space Time Data**  
Dr. Ewan Masters, Bernd Hirsch, and Ken Wong, The University of New South Wales .................. 61-69

**Innovative Integration of GPS, Radiological Measuring Equipment, and GIS to Conduct Radiological Walkover Survey**  
Celeste Barry, Jeff Sims, and Carl Efird, Bechtel National, Inc. .................. 71-77

**GPS in Swedish Forestry**  
Sverker Johansson, SkogFors, The Forestry Research Institute of Sweden .................. 79-83

**GIS Data Collection Using the GPSVan Supported by a GPS/Inertial Mapping System**  
Dr. Josef Coetsee and Dr. Alison Brown, NAVSYS; Dr. John Bossler, Ohio State University. .................. 85-93

**Session A2 (part 1): GPS FOR SURVEYING: NEW DEVELOPMENTS AND APPLICATIONS**

**The Use of Continuous GPS Tracking for Deformation Studies in Southwestern British Columbia**  
Dr. Herb Dragert & Michael Schmidt, Geological Survey of Canada;  
Xin Chen, University of New Brunswick ........................................ 97-103

**Real-Time Rapid-Static and Kinematic Surveying at the Centimeter Level and Below**  
Andreas Mathes and Michail Gianniou, Institute of Physical Geodesy .................. 105-113

**On the Spectrum of the GPS DD-Ambiguities**  
Dr. Peter Teunissen, Paul de Jonge, and Christiaan Tiberius, Delft University of Technology .................. 115-124

**Session B1: GPS USER EQUIPMENT TECHNOLOGY**

**Extending Narrow-Correlator Technology to P(Y)-Code Receivers: Benefits and Issues**  
Steven Karels and Thomas Macdonald, TASC; Dr. Mats Viggh, Transmission Lines, Inc.;  
Robert Balla, Ground Based Radar Project Office .......................... 127-132

**C/A Code Pseudoranging Accuracy - How Good Can It Get?**  
Dr. Lawrence Weill, Magellan Systems Corporation & California State University, Fullerton .................. 133-141

**A Practical Approach to the Reduction of Pseudorange Multipath Errors in a L1 GPS Receiver**  
Bryan Townsend and Patrick Fenton, NovAtel Communications Ltd. .................. 143-148

**Implications of “Z” Technology for Civilian Positioning**  
Dr. Sergei Gourevitch, Ashtech Inc. ........................................ 149-155
A Special Method of Managing Multipath Effects

Position Accuracy Improvement Using Fuzzy Processing on GPS Data
Dr. Kazunobu Koremura, Michihiro Asakura, & Chiaki Matsumoto, Electronic Navigation Research Inst. ........ 165-172

Software Considerations for the Interrupted Data Acquisition Receiver
Gerald Whithut, Navstar Systems Ltd. ........................................................... 173-178

An Overview of the GPS Standard Positioning Service Signal Specification
Rob Conley, Overlook Systems Technologies, Inc........................................... 179-188

Session C1: UNIQUE APPLICATIONS

A Novel Use of GPS for Determining the Orbit of a Geosynchronous Satellite:
The TDRS/GPS Tracking Demonstration
Dr. Bruce Haines, Dr. Stephen Lichten, Ronald Muellerschoen, Don Spitzmesser, Jeffrey Srinivasan, Scott Stephens, & Dr. Lawrence Young, Jet Propulsion Laboratory; Dr. Dennis Sweeney, Virginia Tech ........ 191-202

DGPS Navigates Forestry Vehicles in Real-Time
René Levesque, Forest Engineering Research Institute of Canada .......................................................... 203-204

Electronic Toll Collection Based on GPS - Experiences With the MANNESMANN Project ROBIN
Dr. Uwe Albrecht, Andreas Widi, and Günther Weber, Mannesmann Pilotentwicklung ......................... 205-209

An Application of On-The-Fly Kinematic GPS to an Airborne Laser Terrain Profiling & Imaging System
Morgan Reed, Dr. Dariusz Lapucha, Kenneth Werther, Jr., and Larry Rosenbalm, John E. Chance & Associates, Inc. ........................................... 211-219

The Use of GPS Buoyes to Calibrate Altimetric Satellites
Mike Park, George Born, Penny Axelrad, Kenn Gold, Kevin Key, and Dan Kubitshek, University of Colorado; Tom Keelsey and Jimmy LaMance, NAVSYS Corporation; Chris Rocken and Jim Johnson, UNAVCO; E.J. Christensen, Jet Propulsion Lab; Richard Eanes, University of Texas at Austin ....................... 221-230

Solving the 9-1-1 Mapping Problem with GPS
Keith Cunningham, Spatial Data Research/Sokkia Technology ......................................................... 231-235

Multisensor GPS-Based Recreational Trail Mapping
Dr. James Wolper, Dr. Shamim Mohamed, Idaho State University; Stoney Burt, & Ron Young, AMI, Inc. .... 237-244

The GPS Burst Detector W-Sensor
Dr. Dennis McCrady, ITT A/CD; Paul Phipps, Sandia National Laboratories ........................................... 245-250

Evaluation of GPS Performance in Mobiflex Alarm, a Vehicle Location System
Roger Bengtsson, Telia Research AB ............................................................ 251-258

Session D1: NAVIGATION SATELLITE TECHNOLOGY

Recent MCS Improvements to GPS Timing
Capt. Steven Hutsell, 2nd Space Operations Squadron, Falcon AFB .......................................................... 261-273

Between Sun and Earth: Solar Pressure State Estimation in the GPS Master Control Station
Capt. Ronald Smetek, Jr., U.S. Air Force; John Taylor, IV, Martin Marietta Corporation .......................... 275-284

Improved WGS 84 Coordinates for the DMA and Air Force GPS Tracking Sites
Everett Swift, Naval Surface Warfare Center .......................................................... 285-292

The Russian GLONASS System: A US Air Force/Russian Study
Scott Fearheller, U.S. Air Force ................................................................. 293-304

GPS/GLONASS Time Difference Measurements and Test Bed Development
Benjamin Peterson, Eric Chamberlin, and Terry Vogler, U.S. Coast Guard Academy; Peter Daly and Stuart Riley, University of Leeds ......................................................... 305-312

Full Automated System for Receiving and Processing GLONASS Data
Dr. Yuri Gouzhva, Dr. Arvid Gevorkyan, Dr. Pytor Bogdanov, and Vitaly Ovchinnikov, Russian Institute of Radionavigation and Time .......................................................... 313-316

Combat Survivor Evader Locator (CSEL): Requirements and Progress
James Fong, SMC/XRF U.S. Air Force ............................................................. 317-325
Session A2 (part 2): GPS FOR SURVEYING: NEW DEVELOPMENTS AND APPLICATIONS

Acceptance of Real-Time Kinematic by the Professional Surveyor
Timo Allison, Peter Griffioen, and Nicholas Talbot, Trimble Navigation ........................................... 329-337

A Comparison of Geodetic Receivers Under A-S Conditions Survey of Baselines
Piet Sluiter, Consultant; Jeroen Zomerdijk, Ministry of Transport; George Husti, TU Delft ......................... 339-351

Calibration of Multipath Errors on GPS Pseudorange Measurements
Dr. Changdon Kee and Dr. Bradford Parkinson, Stanford University ......................................................... 353-362

Comparison of Several AROF Kinematic Techniques
Ronald Hatch, GPS Consultant; Dr. Hans-Juergen Euler, Leica AG ......................................................... 363-370

Determining Deflection of the Vertical with GPS
Edward Mogilevsky and Yosef Melzer, Survey of Israel ........................................................................... 371-374

Earthquake Research Yields Manhour-Efficient Point with Millimeter Precision
Dr. Andrea Donnellan and Dr. Kenneth Hurst, Jet Propulsion Laboratory;
Carl Carter and Patricia Romanowski, Allen Osboure Associates ......................................................... 375-381

GPS Results are Consistent with VLBI
Dr. John Gipson, Jim Ryan, Edwin Himwich, and Dr. Tom Clark, Goddard Space Flight Center .................. 383-390

Geodynamic GPS EXTENDED SAGET Network in Central Europe
Dr. Janusz Sledzinski, Warsaw University of Technology ............................................................................ 391-398

A Batch Least Squares Implementation for Estimating Autonomous GPS Point Positions
Annabelle Colestock, Applied Research Lab, University of Texas ............................................................. 399-404

Session B2: INTEGRATED SYSTEMS

Neural Network Loran-C Calibration Using GPS
Dr. Alexey Cherepakhin, Dr. Yaokun Zhong, and Daniel Greenwood, NETROLOGIC, Inc. ...................... 407-416

Using Low Cost Inertial Sensors for Integrated Satellite-Inertial Navigation
Stefan Vieweg, Institute of Flight Guidance and Control, TU Braunschweig ............................................. 417-425

Operational Results in a Full-integrated Aircraft Navigation System with Standard Avionic
Using DGPS, MLS and DME/P
M.A. Martinez and Dr. M. Pérez, GMV S.A.; R. Román and L. Andrada,
Aeropuertos Españoles y Navegación Aérea - AENA ............................................................................. 427-442

A Universal GPS/INS Kalman Filter Design
Gene Howell and Dr. Wang Tang, ARINC Research Corporation .............................................................. 443-451

Compact Circuitry for GLONASS Reception
Dr. Oliver Leisten, Navstar Systems ............................................................................................................. 453-459

Fully Integrated GLONASS Dual Frequency P-Code and GPS/GLONASS
Single Frequency C/A Code Receiver: Features and Performance
Anushia Balendra, Sonia Kim, and Jacques Beser, 3S Navigation ............................................................ 461-470

Precise DGPS and Self Calibrating Laser Altimetry for Airborne Marine Geoid Determination
A. Geiger, M. Cocard, Y. Peter, and H-G. Kahle, GGL-ETHZ .................................................................... 471-476

Silicon Inertial and GPS Guidance for Gun Launched Munitions
Mahendra Singh, Waddan Systems; John Fraysee, NSWC Dahlgren; Sanjai Kohli, STS Inc. ...................... 477-482

Session C2: LAND/VEHICULAR

Projected Navigation System Requirements for Intelligent Vehicle Highway Systems (IVHS)
D. Jim Chadwick, The MITRE Corporation ................................................................................................. 485-490

Open Architecture, A New Concept in Vehicle Location Systems
Lynn Stoddart, TransTrak, Inc. .................................................................................................................... 491-499

Mobiflex Alarm, a Vehicle Location System Based on Open Subsystem Interfaces
Roger Bengtsson, Eric Wichtel, and Magdalena Akke, Telia Research AB ................................................. 501-508

GPS Installation on Federal Railroad Track Geometry Vehicle
John Conner, II, Empire Digital Instruments; Bdale Garbee, Garbee and Garbee;
Carl Fischer, Federal Railroad Administration ............................................................................................ 509-518
Real-time On-the-Fly Ambiguity Resolution Over Short Baselines in the Presence of Anti-Spoofing
Ming Yang, Clyde Goad, and Burkhard Schaffrin, Ohio State University ........................................ 519-525

Seasonal Effect of Tree Foliage on GPS Signal Availability and Accuracy for Vehicular Navigation
G. Lachapelle, J. Henriksen, and T. Melgara, The University of Calgary ........................................... 527-532

Results of a Study Into the Utility of Carrier Phase GPS for Automated Highway Systems
Randal Galijan, James Gilkey, and Richard Tumer, SRI International .............................................. 533-541

Kinematic GPS in a Robotic Vehicle
Yingfeng Li and Phillip Noe, Texas A&M University ............................................................................ 543-546

Traffic Accident Vehicle Position Location on Florida's Highways Using Differential GPS
Dr. Ramesh Shrestha, University of Florida ......................................................................................... 547-554

Session D2: GPS INTEGRITY

A Partial Identification RAIM Algorithm for GPS Sole Means Navigation
R. Grover Brown, Iowa State University; John Kraemer, U.S. Department of Transportation;
Giau Nim, Volpe National Transportation Systems Center ............................................................... 557-566

A New Approach to GPS Integrity/Availability: Immediate Global Sole Means Without WAAS
Dr. John Diesel, Litton Aero Products ...................................................................................................... 567-576

Impacts of Ionospheric Fading on GPS Navigation Integrity
Gregory Bishop and Dr. Santimay Basu, Phillips Laboratory (AFMC);
Elizabeth Holland and James Secan, Northwest Research Associates ............................................. 577-585

RAIM Availability for Augmented GPS-Based Navigation Systems
William Michelson, Jonathan Bernick, Peter Levin, and Per Enge, Worcester Polytechnic Institute ....... 587-595

PPS RAIM Algorithms and Their Performance
Karl Kovach, Diane Davis, and Hana Maquet, ARINC ......................................................................... 597-607

Autonomous Integrity Monitoring for GPS-Based Precision Landing Using
Ground-Based Integrity Beacon Pseudolites
Boris Pervan, Dr. Clark Cohen, David Lawrence, H. Stewart Cobb, Dr. J. David Powell,
and Dr. Bradford Parkinson, Department of Aeronautics and Astronautics, Stanford University .......... 609-618

RAIM Detection and Isolation Integrity Availability With and Without CAG
Dr. Mohan Ananda, Dr. Jum Leung, Dr. Prem Munjal, and Barry Siegel, The Aerospace Corp. .......... 619-630

Monitoring Differential GPS Who Will Guard The Guards?
Michael Barnes, Racal Survey USA Inc.; Gordon Johnston, Racal Survey Limited, UK ....................... 631-637

Optimization of Add-On Satellites to GPS
Pierre Janniere and Dr. Erick Lansard, Alcatel Espace; Thierry Boquillon, ENSAE ................................. 639-642

Session A3: ATTITUDE DETERMINATION SYSTEMS AND RESULTS

Assessment of a Non-Dedicated GPS Receiver System for Precise Airborne Attitude Determination
Dr. M. Elizabeth Cannon and Huangqi, The University of Calgary;
Todd Owen and Mark Meindl, Sandia National Laboratories ............................................................... 645-654

Use of Signal-To-Noise Ratio for Multipath Error Correction in GPS Differential Phase Measurements:
Methodology and Experimental Results
Dr. Penina Axelrad, Christopher Comp, and Peter MacDoran, University of Colorado .......................... 655-666

Techniques to Achieve Ultra-Precise Attitude Determination for Large Baselines
Steven Karels and Thomas Macdonald, TASC; Dr. Mats Vigg, Transmission Lines, Inc.;
Robert Balla, Ground Based Radar Project Office .............................................................................. 667-673

Dynamic GPS Attitude Performance Using INS/GPS Reference
C. McMillan, Defence Research Establishment Ottawa; Dale Arden, Dale Arden Consulting;
Gerard Lachapelle and Gang Lu, The University of Calgary ............................................................... 675-682

Instantaneous GPS Attitude Tests: Cycle Ambiguity Resolved
Geoffrey Hazel and Stacey Smith, Adroit Systems, Inc. ........................................................................ 683-688

Design Considerations and Operational Results of an Attitude Determination Unit
Mark Kuhl, Dr. Xinhua Qin, and William Cottrell, Ashtech, Inc. ............................................................. 689-696
Session B3: TESTING GPS SYSTEMS

Real Time, Multiple Model Simulator Laboratory for GPS Related System Testing
1Lt. Kevin Payne, 46th GTS, Holloman AFB; Rick Kurtz, TRW ........................................... 729-736

Testing Differential GPS Using Satellite Signal Generators
Marvin May and Joe Weiss, NRaD; John Haiges, Galaxy .......................................................... 737-746

Examination of a Distributed Architecture GPS Simulation Test Bed
Kevin Bartrop and Bryant Elrod, Stanford Telecom ................................................................. 747-754

The CIGTF High Accuracy Post-Processing Reference System (CHAPS)
Capt. Britt Snodgrass and Capt. John Raquet, 46th GTS, Holloman AFB ..................................... 755-763

GPS Based TSPI for DOD Ranges RAJPO HDIS Test Results
Samuel Burkett, Ill, Mohammed Miran, Dr. Sultan Mahmood, Jeannine Yakoboski, and
Frank Fieldson, Sverdrup Technology, Inc. ........................................................................... 765-772

FAA’s Wide Area Augmentation System (WAAS) Test Concepts for Early Implementation
Robert Till & William Wanner, FAA Technical Center; Robert Loh, Innovative Solutions International.............................................................. 773-781

A Kinematic Carrier Phase Tracking System for High Precision Trajectory Determination
Dr. Wang Tang, Dale Turley, Gene Howell, ARINC; Linda Wilkinson, Hughes Aircraft Company ................................................................. 783-789

Near Real Time GPS Simulator Integrated with the Manned Flight Simulator
Christopher Bartone and Frederick Ventrone, Jr., NAWC-AD; Gary Green, Pacer Systems, Inc. ................................................................. 791-797

Initial Report of Activities of the GPS Test Standardization Working Group
Stewart Teasley, Rockwell; Darwin Abby, Intermetrics ............................................................. 799-804

Session C3: MILITARY

GPS Exploitation for Precision Targeting: Results
George Beck, James Dare, Joseph Kaiser, and Carlos Bedoya, McDonnell Douglas Aerospace;
Todd Jenkins and Pete Howe, Wright Lab, WPAFB ................................................................. 807-816

Limitations of GPS Jamming Models in Providing Definitive Jamming Assessments
Capt. Jay Purvis, U.S. Air Force ............................................................................................... 817-822

GPS Performance Under Aircraft Masking Conditions: AGM-130 Flight Demonstration
with Midcourse Guidance
Roy Kerfoot, Jr., Rockwell Tactical Systems Division; Wilmer Mickelson and Larry Vittorini,
Rockwell Collins Avionics & Communications Division; John Nielson, Nielson Consultants ................................................................. 823-839

Accuracy Comparison of GPS and an Inverse GPS Locating System
Dr. James Watson, Dr. Fred Shimabukuro, and Dr. David Schwartz, The Aerospace Corp. ................................................................. 841-850

Relative GPS Using DME/TACAN Data Link
James Waid and Dennis King, E-Systems .................................................................................. 851-861

An Analytical Study of Fast Acquisition Issues in GPS Exploitation for Electronic Combat
Dr. Sultan Mahmood and Colleen Stewart, Sverdrup Technology, Inc.; Neeraj Pujara, Wright Laboratory ................................................................. 863-870

Analysis of a Completely Integrated INS/GPS Navigation System for Re-Entry Vehicles
Erwin Lohnert and Dr. Bernd Eissfeller, University FAF; Dr. Otto Wagner, TU Munich ................................................................. 871-881

New Theories and GPS Experiments About Effects of Multipath and RF Jammers
René Landry and Shahzad Mahooti, ENSAE ............................................................................. 883-897

TIDGET Applications for Missile Tracking and Guidance
Dr. Alison Brown and Dr. Thomas Kelecy, NAVSYS Corporation ................................................... 899-906
Session D3: AIRBORNE NAVIGATION: GROUND SUPPORT

GPS and Air Traffic Control: Start With a Clean Sheet of Paper
Donald Tilden, Embry-Riddle Aeronautical University ................................................................. 909-911

DGPS For Seamless Airport Operations
Lois Valliere Pilley and H. Robert Pilley, DSDC ................................................................. 913-921

Communication Protocols for GPS-Based Surveillance and TCAS
Ran Gazit and Dr. J. David Powell, Stanford University ................................................................. 923-932

Jammers in the Commercial World of GPS
Blane Wollschlager, Rockwell ......................................................... 933-937

Aircraft Surveillance Based on GPS Position Broadcasts from Mode S Beacon Transponders
Edward Bayliss, Robert Boisvert, Michael Burrows, and William Harman, MIT Lincoln Laboratory ................................................................. 939-950

Aspects Concerning Civil GNSS
Ph. Hartl and K.-H. Thiel, Institute of Navigation, University of Stuttgart ................................................................. 951-954

Accurate Positioning in a Flight Inspection System Using
Differential Global Navigation Satellite Systems
Cecelia Feit and Martin Bates, Sierra Research ................................................................. 955-964

The Use of Airborne Differential GPS to Detect Coordinate and Calibration Errors in DME Navigation Aids
Prof. Vidal Ashkenazi, Dr. Terry Moore, and Dr. Chris Hill, IESSG;
Dr. John Storey, Rowland Rawlings, and Conrad Cleasby, EUROCONTROL ................................................................. 965-972